

NodeBots Demo Night

#### Machine Learning & Bad Robots

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## About Me

#### • UK

- Early 90s : PhD in Machine Learning
- New York
  - Started finance-related Internet business in 1999
  - Fixed Income Trading business 2002 ...

#### Singapore

- Arrived in Sept 2013
- Getting back to Machine Learning roots



### Industrial Robots



#### Pros

- Precision
- Power
- 24 / 7 operation

#### Cons

- Dumb precision & Power => safety hazard
- Cost
- Difficult to re-purpose



## **CoWorking Robots**



#### Pros

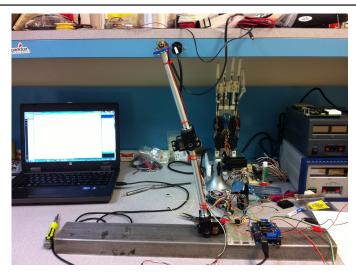
- Compliant : Safe
- Teachable
- Disruptive Price-Point

#### Cons

- Lack of Power : Slow
- New Market



## "Bad Robots"







#### Qualities

- Low w.r.t. Mechanical stuff
- High w.r.t Sensor stuff
- High w.r.t Software stuff
- Even more disruptive price



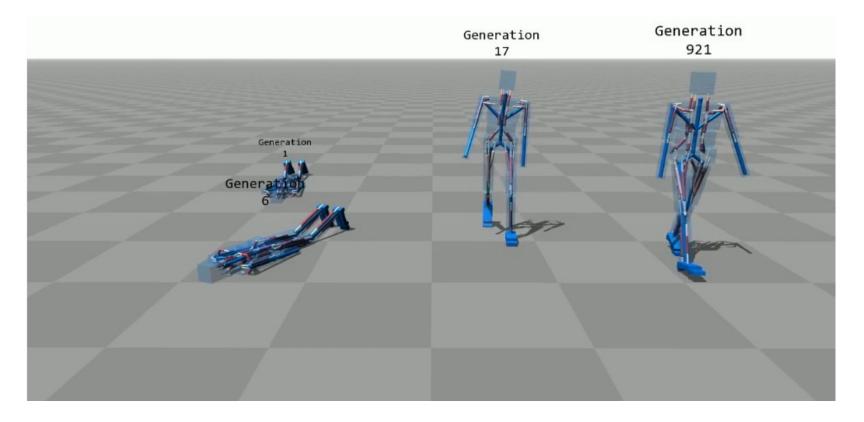
## Machine Learning

- Optimal Control = IMPRACTICAL
  - Perfect is enemy of Good
- Adaptive Systems = REQUIRED
  - Need to learn regions that can be controlled
  - Need to learn to adjust control within regions
- Machine Learning Paradigms
  - Neural Networks / Tree methods
  - Reinforcement Learning (e.g.: Q-Learning)
  - Ensemble methods
  - Evolutionary methods



## Quick Video : Evolution

http://vimeo.com/79098420





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### Conclusion

This is a very exciting time!

- Hardware inflection point
  - Though it's still HARD ...
- Software-ize everything



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# **Enabling Technologies**

- Rise in Cheap Embedded FLOPs
  - Arduino ...
  - ... ARM boards (STM32Fn, BeagleBone, Raspberry Pi)
- Brushless Motors becoming 'easier'
- Cheap phone components
  - eg: Accelerometer / Gyroscope / Barometer / Compass
- Vision
  - Webcams, Phone cameras
  - Mice



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### Quadrotors

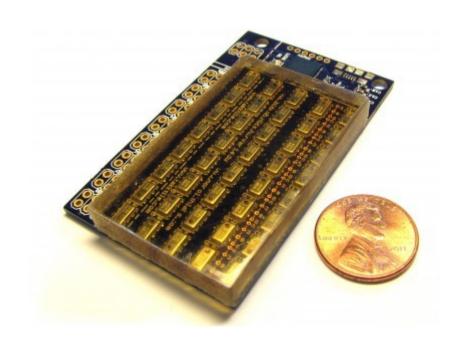


#### • Enabling Technology :

- Brushless Motors
- FLOPs (moving from Arduino -> ARM)
- Sensors galore
- [ still need better batteries ]
- Bad Robot?
  - Solve bad environment for cameras with Gimbal



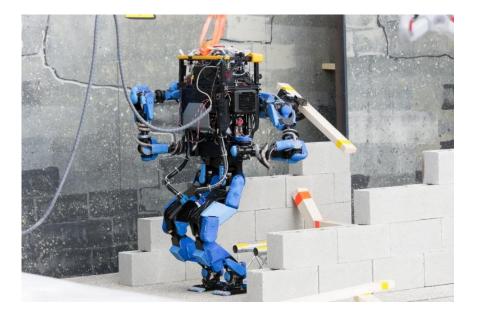
## Sense of Touch



- "Touch" is a problem
- Pick any Two:
  - Accuracy
  - Robustness
  - Low Price
- Enabling Technology:
  - Barometer (from Phone)



## SCHAFT Humanoid - DARPA



#### Brushless Actuators:

- Liquid cooled
- Computer-controlled
  Overdrive
- Capacitor for Amps

#### • Active Control:

- Look-ahead for motion planning
- Backing :
  - Now a Google company...



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